**Meeting minutes 10/28/15**

Meeting Preamble

Prior to the meeting the Arduino was found to be producing less than 5V to components. Bruce stated he was going to determine the Arduino output by comparing performance to a separate Arduino.

Meeting

The robot build was presented to members in attendance and a previous rundown of what was done so far was covered. Discussion of how to program the robot looks to explore iterative software to write the walking program for us. Concern for the program storage capabilities was expressed. Due to the Arduino output being in question the Arduino was not wired during the meeting.

Fallow up

1. Arduino voltage output
2. Automated software for programing walking
3. Arduino storage capabilities
4. Robot’s backwards arm